

Mingyi Wang

College of Control Science and Engineering, Zhejiang University
wmyn0908@gmail.com — [Personal Homepage](#) — +(86) 18888915807

EDUCATION

Zhejiang University

M.E. in Electronic Information

Zhejiang, China

09/2022 – 06/2025

- College of Control Science and Engineering
- **Advisors:** Prof. Guang Li and Prof. You Wang

Zhejiang University

B.E. in Automation

Zhejiang, China

09/2018 – 06/2022

- College of Control Science and Engineering
- Cumulative GPA: **3.90/4.00 (Top 10%)**

RESEARCH INTERESTS

Mobile Robots, Autonomous Driving, Reinforcement Learning, Behavioral Planning and Prediction

SELECTED PUBLICATIONS

1. **Wang, M.***, Wang, J.*, Ye, T., Yu, K., Chen, J. (2025). “Do LLM Modules Generalize? A Study on Motion Generation for Autonomous Driving.” *9th Conference on Robot Learning (CoRL 2025)* [**Accepted**]. [[Project Page](#)]
2. **Wang, M.**, Zou, H., Liu, Y., Wang, Y., Li, G. (2024). “A Joint Prediction Method of Multi-Agent to Reduce Collision Rate”. *2024 China Automation Congress (CAC)*. [[Paper](#)]
3. Li, H., **Wang, M.**, Gao, H., Zhao, S., Li, G., Wang, Y. (2023). “Hybrid Silent Speech Interface Through Fusion of Electroencephalography and Electromyography”. *2023 Conference of the International Speech Communication Association (INTERSPEECH)*. [[Paper](#)]
4. Zhang, Z., Zou, Z., Li, X., **Wang, M.**, Wang, Y., Guan, X., Wang, Y. and Li, G. (2023). “Path Planning for Autonomous Driving with Curvature-considered Quadratic Optimization”. *2023 IEEE Intelligent Vehicles Symposium (IV)*. [[Paper](#)]
5. Zou, Z., Zhang, Z., Lu, Z., Li, X., **Wang, M.**, Wang, Y., Hao, J. and Li, G. (2023). “Discrete States-Based Trajectory Planning for Nonholonomic Robots”. *2023 IEEE International Conference on Robotics and Biomimetics (ROBIO)*. [[Paper](#)]
6. Lu, Z., **Wang, M.**, Yu, S., Wu, Y., Wang, Y. and Li, G. (2023). “Camera-Lidar-Based Terrain Multi-type Classification Using Both Spatial and Histogram Features of Lidars”. *2023 3rd International Conference on Computer, Control and Robotics (ICCCR)*. [[Paper](#)]

RESEARCH & WORK EXPERIENCE

★ [AutoLab](#) & [UDEER.AI](#) (Former Alibaba DAMO Academy Autonomous Driving Team)

Advised by Associate Prof. [Kaicheng Yu](#) and Dr. [Junbo Chen](#)

05/2024 — 05/2025

- **Reinforcement Learning for Motion Generation** [[Project Page](#)]
- Implemented [MotionLM](#) from scratch, proposed an autoregressive trajectory prediction model capable of generating agent action sequences in a GPT-like manner. This also ensures that the generated trajectory actions are differentiable. Our approach can generate the trajectories of all agents in a scene using a single inference (rollout), and employs a sampling method to model trajectory multimodality.
- Proposed a reinforcement learning method using the Advantage Function to mitigate the Out of Distribution issues, enabling our model to outperform previous approaches.
- During the reinforcement learning process, our model overcomes the issue of low interaction efficiency between the agent and the environment by directly utilizing model rollouts to sample sequences for MCTS, making it highly efficient compared to previous reinforcement learning methods.
- We wrote a paper titled “Do LLM Modules Generalize? A Study on Motion Generation for Autonomous Driving,” which has been **accepted** to the Conference on Robot Learning (**CoRL**) 2025.

★ **ZHUOYU(DJI Automotive) - Planning and Control Department**

Shenzhen, China

Advised by Dr. **Lu Zhang**

08/2023 — 02/2024

- **Multi-agent Motion Prediction [Paper]**: Drawing on insights gained from this research experience, I proposed a method for generating scene-consistent multi-agent trajectories aimed at reducing collision rates.
- Developed a learning-based planning model inspired by trajectory prediction, utilizing perceptual inputs to generate planned paths and cost maps for downstream routing and evaluation.
- Awarded “Sprint Star” for outstanding performance in the planning and decision-making department, becoming the first intern to receive this honor independently.

★ **Spherical Robotics Laboratory(Luoteng Technology)**

Hangzhou, China

Advised by Associate Prof. **You Wang**

09/2022 — 07/2023

- **Discrete State Trajectory Optimization [Paper]**: Based on DSTP, I incorporated kinematic constraints of spherical robots into trajectory optimization modeling.
- Using a discrete state optimization framework and the L-BFGS optimizer, I transformed the constraint problem into a soft constraint problem, generating real-time and high-quality trajectories.
- Our spherical robot project was awarded the Gold Medal at the 18th “Challenge Cup” in Zhejiang Province(2/18).

★ **ZJU Undergraduate Graduation Project**

Hangzhou, China

Advised by Prof. **Guang Li**

11/2021 — 10/2022

- **Silent Speech Interface Through Bioelectric Signals [Paper]**
- Designed the experimental protocol for electroencephalography(EEG) and electromyography(EMG) data collection, and gathered data from multiple participants to build a dataset.
- Proposed a deep learning method that combines EEG and EMG signals, integrated with a vocoder, to reconstruct speech from muscle movements. This research has the potential to assist individuals with aphasia in producing speech.

HONORS & AWARDS

- 2019 First-Class Scholarship of Zhejiang University (**top 5%**)
- 2019 Zhejiang Provincial Government Scholarship (**top 5%**)
- 2020 First Prize in the 12th National College Student Mathematics Competition
- 2020 Zhejiang University Kindness Scholarship
Awarded for outstanding contributions made during volunteer teaching in Haidong, Qinghai Province
- 2022 Honored Graduate of Zhejiang University
- 2022 Honored Graduate of Zhejiang Province (**top 5%**)

SKILLS

- **Programming**: Python, PyTorch, C/C++, Git, Matlab.
- **Robotics**: ROS, Linux, IoT chips(STM32, Arduino).
- **Soft skills**: Responsible, collaborative, and possessing a positive and proactive attitude toward challenges.